

The CPLA PLAN - A balanced development

Research and Resource Development

Resources under development

1. Guides
 - Conceptualising Learner Autonomy
 - Enquiry Based Learning
 - Student Partnerships
2. Newsletters
3. Web-based and video resources
4. Annotated bibliography on Learner Autonomy
5. Conference papers and presentations
6. Books
 - Learner Autonomy: Principles and Practice
 - Learner Autonomy Across the Curriculum

Case studies gathered from the first two years of CPLA

Mark Boylan (D&S)
Collaborative Learning: Supporting Learner Autonomy in Professional Education

Mike Bramhall (ACES)
Promoting Learner Autonomy in Engineering by Students Using Media

Claire Craig (HWB)
Enquiry Based Learning and IT Skills in Occupational Therapy

Roger Lloyd Jones (D&S)
Disseminating Good Practice through Learner Autonomy and Enquiry Based Learning on a History Programme

Peter Long (O&M)
Overcoming the Fear of Figures - a new approach to Business Analysis

Richard Lynch, (D&S)
Changing Assessment Cultures: Applied Social Science Programme

Karen Nicholls (LITS)
International Students' Transition to UK HE

Nick Nunnington (D&S)
Promoting Learner Autonomy through Problem Based Learning, Role Play and the Use of 'Students as Consultants, Tutors as Clients'

Christine O' Leary (O&M)
A Faculty Wide Approach to Embedding Assessment for Learning

Will Reader, (D&S)
Assessment by Review and Practice by Wiki: Explorations in Learner Autonomy

John Reidy (ACES)
Improving Maths Self-confidence and Maths Thinking Skills

Anthony Rosie (D&S)
Professional Learning Week

The CPLA is working to produce a range of resources to support practices in developing learner autonomy. These resources arise as a result of research and evaluation activity as well as the outcomes of supported projects and initiatives. Collectively, we are developing a range of resources, which are offered through our website.



**Sheffield
Hallam University**

SHARPENS YOUR THINKING

**Centre For Excellence in Teaching and Learning
Centre For Promoting Learner Autonomy**
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